

# Aggregative Efficiency of Bayesian Learning in Networks

Krishna Dasaratha    Kevin He

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# Social-Learning Dynamics in Different Networks

- **Social learning:** info about unknown state dispersed among society of agents, agents act based on private signals and observations of social neighbors
- How does social network affect efficiency of info aggregation?
- Esp. relevant today as communication technology reshapes networks: Facebook, Twitter, ...
- Existing work focuses on complete network
- Open question: impact of network on how well signals are aggregated — and hence how quickly rational agents learn

*Golub and Sadler (2016): “A significant gap in our knowledge concerns short-run dynamics and rates of learning in these models. [...] The complexity of Bayesian updating in a network makes this difficult, but even limited results would offer a valuable contribution to the literature.”*

## Environment and Key Results

Introduce **tractable model of rational sequential learning** that lets us compare learning dynamics across different networks

- rich signals, rich actions: Gaussian private signal, infer neighbors' beliefs perfectly from their actions
- strips away other sources of learning-rate inefficiency
- unique equilibrium of social-learning game has **log-linear form**

Highlight **network-based informational confounds**

- suppose 2 and 3 see 1, but 4 sees only 2 and 3
- 1's action confounds the info content of 2 and 3's behavior
- show how rational agents solve this **signal-extraction problem**

**Generations network** – observe subset of agents in previous gen

- express learning rate as simple function of network parameters
- extent of info loss: under a symmetry condition, learning aggregates **no more than 2 signals per gen** asymptotically
- applications to org structure: (1) value of mentorship in organizations; (2) benefits and costs of information silos

## Related Literature

### Sequential social learning

- Banerjee (1992), Bikhchandani, Hirshleifer, Welch (1992)
- **Correct learning** under mild conditions: Acemoglu, Dahleh, Lobel, Ozdaglar (2011), Lobel and Sadler (2015). This paper: [speed](#).

### Obstructions to the efficient learning rate in sequential social learning

- **Coarse action space**: Harel, Mossel, Strack, Tamuz (2020), Rosenberg and Vieille (2019), Hann-Caruthers, Martynov, Tamuz (2018)
  - ▶ HMST's "rational groupthink": trapped in wrong consensus for a long time as small belief changes are not reflected in actions
  - ▶ Rate of learning efficient if actions were rich
- **Endogenous info**: Burguet and Vives (2000), Mueller-Frank and Pai (2016), Ali (2018), Lomys (2019), Liang and Mu (2020).
- This paper: [network-based](#) obstructions to fast learning.

Lobel, Acemoglu, Dahleh, Ozdaglar (2009): compare **two specific network structures** with nbhd size 1. This paper: [arbitrary fixed networks](#). Info confounding only appears in networks with nbhd size  $> 1$ .

Speed of learning under **non-rational heuristics**: Ellison and Fudenberg (1993), Golub and Jackson (2012), Molavi, Tahbaz-Salehi, Jadbabaie (2018). This paper: [rational learning](#).

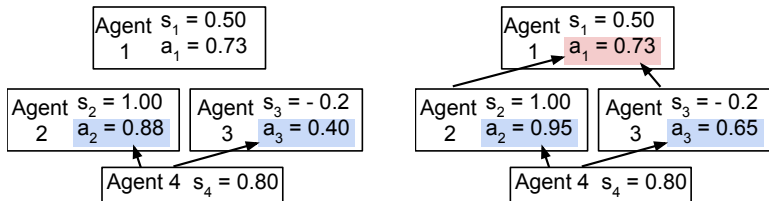
# Outline

1. Setup and example of informational confound
2. Characterization results
  - 2.1 Log-linearity of the equilibrium
  - 2.2 Signal-counting interpretation of equilibrium accuracy
  - 2.3 Condition for long-run learning
3. The generations network
  - 3.1 Learning rate when agents fully observe the previous generation
  - 3.2 Applications: mentorship, information silos
  - 3.3 Main theorem: learning rate in any symm generations network
4. Efficiency of learning and welfare comparisons
5. Simulations on the robustness of results

## Model and Notations

- Two equally likely states  $\omega \in \{0, 1\}$
- Agents  $i = 1, 2, 3, \dots$  move in order, each acting once
  - ▶  $i$  observes **private signal**  $s_i \in \mathbb{R}$  and actions of **neighbors**,  $N(i) \subseteq \{1, \dots, i-1\}$
  - ▶ picks **action**  $a_i \in [0, 1]$  to maximize expectation of  $-(a_i - \omega)^2$
- Signals are Gaussian and conditionally i.i.d. given state,  $s_i \sim \mathcal{N}(1, \sigma^2)$  when  $\omega = 1$  and  $s_i \sim \mathcal{N}(-1, \sigma^2)$  when  $\omega = 0$
- Neighborhoods define an **observation network**  $M$ , with  $M_{i,j} = 1$  if  $j \in N(i)$ ,  $M_{i,j} = 0$  else.  $M$  is common knowledge.
- A **strategy** for  $i$  specifies  $i$ 's play as a function of:
  1. observed actions from neighbors  $N(i)$ , and
  2. private signal  $s_i$ .
- Sequential nature of game  $\Rightarrow$  there is a unique perfect-Bayesian **equilibrium** strategy profile

## An Example of Informational Confound



- 4 perfectly infers 2 and 3's signals from their actions
- 4's accuracy = 3 signals, fully incorporates info in  $s_2$ ,  $s_3$ , and  $s_4$
- $a_1$  influences both  $a_2$  and  $a_3$ , but is unobserved by 4
- 4 cannot fully incorporate  $s_2$  and  $s_3$  without over-counting  $s_1$
- optimal signal extraction: 4 puts "**2/3 as much weight**" on  $a_2$  and  $a_3$  as in other network
- 4's accuracy = "**3.67 signals**"
  - ▶ (to be formalized soon)

## Log-Linearity of the Equilibrium

WLOG apply log-transformations and work with log-variables

- **log-signal**,  $\tilde{s}_i := \ln \left( \frac{\mathbb{P}[\omega=1|s_i]}{\mathbb{P}[\omega=0|s_i]} \right)$ , **log-actions**,  $\tilde{a}_i := \ln \left( \frac{a_i}{1-a_i} \right)$
- these changes are 1-to-1, so there is a (unique) map from  $i$ 's neighbors' log-actions and  $i$ 's log-signal to  $i$ 's eqm log-action
- next proposition says this map is linear

### Proposition 1

For each agent  $i$  with  $N(i) = \{j(1), \dots, j(d)\}$ , there exist constants  $(\beta_{i,j(k)})_{k=1}^d$  s.t.

$$\tilde{a}_i^* = \tilde{s}_i + \sum_{k=1}^d \beta_{i,j(k)} \tilde{a}_{j(k)}^*.$$

The vector of coefficients  $\vec{\beta}_{i,\cdot}$  is given by

$$\vec{\beta}_{i,\cdot} = 2\mathbb{E}[(\tilde{a}_{j(1)}^*, \dots, \tilde{a}_{j(d)}^*) \mid \omega = 1] \cdot \text{COV}[\tilde{a}_{j(1)}^*, \dots, \tilde{a}_{j(d)}^* \mid \omega = 1]^{-1}.$$



## Discussion of Proposition 1

### Proposition 1

For each agent  $i$  with  $N(i) = \{j(1), \dots, j(d)\}$ , there exist constants  $(\beta_{i,j(k)})_{k=1}^d$  s.t.  $\tilde{a}_i^* = \tilde{s}_i + \sum_{k=1}^d \beta_{i,j(k)} \tilde{a}_{j(k)}^*$ . The vector of coefficients  $\vec{\beta}_i$  is given by

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- For general private signal distributions, Bayesian updating in networks intractable as Golub and Sadler (2016) point out
- Gaussian info structure leads to **log-linear eqm** and **closed-form expression of linear weights** that solve signal-extraction problem: downweight neighbors' log-actions if they have higher equilibrium correlation conditional on  $\omega$
- $\vec{\beta}_i$  depends on network  $M$ , but not on signal precision  $1/\sigma^2$

## Signal-Counting Interpretation of Eqm Accuracy

If  $i$ 's only info is  $n \in \mathbb{N}_+$  indep signals,  $\tilde{a}_i \sim \mathcal{N}\left(\pm n \cdot \frac{2}{\sigma^2}, n \cdot \frac{4}{\sigma^2}\right)$ .

### Definition

Social learning **aggregates**  $r \in \mathbb{R}_+$  **signals by agent**  $i$  if the equilibrium log-action  $\tilde{a}_i^* \sim \mathcal{N}\left(\pm r \cdot \frac{2}{\sigma^2}, r \cdot \frac{4}{\sigma^2}\right)$  in the two states.

- When agents use arbitrary strategy profile (even if log-linear), need not have  $\tilde{a}_i \sim \mathcal{N}\left(\pm r \cdot \frac{2}{\sigma^2}, r \cdot \frac{4}{\sigma^2}\right)$  for **any**  $r \in \mathbb{R}$
- But, **equilibrium** log-actions always admit this kind of signal-counting interpretation, suff. stat for rational accuracy

### Proposition 2

*There exist  $(r_i)_{i \geq 1}$  so that social learning aggregates  $r_i$  signals by agent  $i$ . These  $(r_i)_{i \geq 1}$  depend on the network  $M$ , but not on  $\sigma^2$ .*

- Can help solve for eqm strategy profile in some cases
- $\lim_{i \rightarrow \infty} (r_i / i) \in [0, 1]$  called **aggregative efficiency** of  $M$

## Condition for Long-Run Learning

Say society **learns completely in the long run** if equilibrium actions  $(a_i^*)$  converge to  $\omega$  in probability.

### Proposition 3

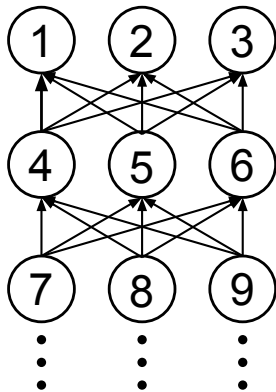
*Society learns completely in the long run if and only if*

$$\lim_{i \rightarrow \infty} \left[ \max_{j \in N(i)} j \right] = \infty.$$

- If we consider the most recent neighbor of each agent, then this sequence of most-recent-neighbors tends to  $\infty$
- Analog of Acemoglu, Dahleh, Lobel, and Ozdaglar (2011)'s **expanding observations** property for deterministic network
- Mild and clearly necessary: else for some  $C < \infty$ , infinitely many  $i$  cannot access the signal of any  $j > C$  except their own
- Long-run learning not a useful way to compare networks
  - ▶ Instead, compare  $(r_i)_{i \geq 1}$  and aggregative efficiency
  - ▶ May have  $r_i \rightarrow \infty$  yet aggregative efficiency far below 1

# The Maximal Generations Network

- $K \geq 1$  agents per generation
- Agents in gen  $t$  observe all agents in gen  $t - 1$



## Proposition 4

*In the maximal generations network:*

- *Society learns completely in the long run with any  $K$ .*
- $\lim_{i \rightarrow \infty} (r_i / i) = \frac{(2K-1)}{K^2}$ .
- *In the long run, social learning aggregates...*
  - ▶ *fewer signals per agent with larger  $K$*
  - ▶ *fewer than 2 signals per generation with any  $K$*
- *For any  $K$  and any  $i, i'$  in generations  $t$  and  $t - 1$  with  $t \geq 3$ ,  $r_i \leq r_{i'} + 3$ .*

## Bounds on Signals Aggregated Per Generation

- Agents in generation  $t$  have observation paths of length  $t - 1$
- Can show in any network, this implies  $r_i \geq t$
- Social learning must aggregate at least 1 signal per gen
- This lower-bound not too far from the actual learning rate:

$$r_i / \underbrace{\lceil i/K \rceil}_{\text{gen of } i} = \underbrace{\frac{(2K - 1)}{K}}_{<2} + o(1)$$

(No more than **2 signals** per gen in long-run, for any  $K$ )

$$r_i - r_{i'} \leq 3, \quad \text{for } i, i' \text{ in gen } t, t - 1 \text{ where } t \geq 3$$

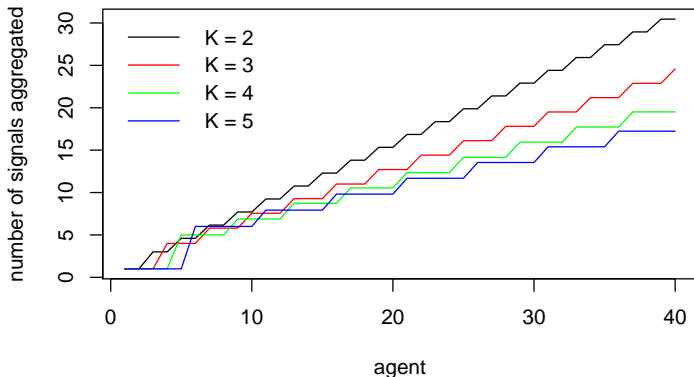
(No more than **3 signals** per gen **starting with gen 3**, for any  $K$ )

- For  $K$  large, individuals only manage to aggregate an unboundedly small fraction of their private signals in eqm

## Slower Per-Agent Rate of Learning with Larger Gens

- If  $K = 1$ , every agent perfectly incorporates all past private signals  $\Rightarrow$  fastest possible speed of social learning
- Prop 4 says aggregative efficiency strictly decreases in  $K$
- Worse learning with larger  $K$  holds numerically starting from agent  $i = 16$  when comparing among  $K \in \{2, 3, 4, 5\}$

**Aggregative Efficiency and Generation Size  $K$**



## Application 1: Value of Mentorship in Organizations

- Many organizations with overlapping cohorts (e.g., colleges, professional firms, etc.) have mentorship programs, pairing each newcomer with someone from the previous cohort

### Corollary 1

*In the maximal generations network, if each agent additionally observes the **private** signal of one agent from the previous generation (their “mentor”), then  $r_i \geq i - K$  for every  $i$  and aggregative efficiency is 1.*

- Incumbents behave based on individual private info and shared org knowledge (e.g., key internal events in company's recent past)
- Newcomer is unaware of org knowledge, so becomes confused about incumbents' behavior
- De-confounding role of mentors: personal details of just one individual's experience can help interpret everyone's behavior

## Application 1: Value of Mentorship in Organizations

Management literature discusses a related “socializing” benefit of mentors.

Chao (2007) in *The Handbook of Mentoring at Work: Theory, Research, and Practice*:

*“Mentors can be powerful **socializing agents** as an individual adjusts to a new job or organization. As protégés learn about their roles within the organization, mentors can help them **correctly interpret their experiences** within the organization’s expectations and culture.”*

In our setting, it is this “interpretive” value of mentorship that helps build a more effective learning organization.

- If mentors generate new signals instead of sharing past signal realizations, social learning does not speed up very much

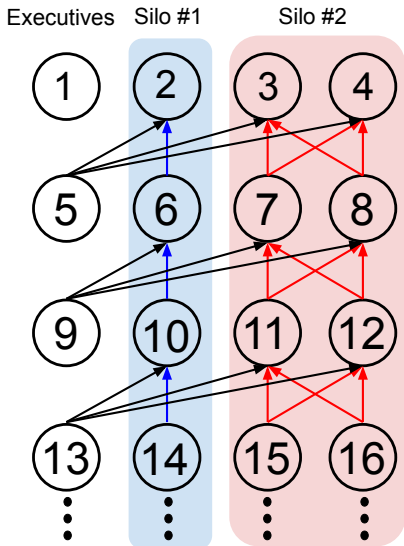


## Application 2: Information Silos in Organizations

**Information silos:** In management, describes info fragmented among subgroups that do not communicate with each other

- Gillian Tett's 2015 book *The Silo Effect* documents prevalence of silos in government bureaucracies, technology firms, banks
- E.g. departments in the same municipal government, product divisions in a company, ...
- Causes: pay structure discourages collaboration across silos, technical barrier prevents flow of ideas across specialties, ...
- Silos persist for decades, as cohorts of new workers join the organization and bring in new info
- Tett (2015) joins a consensus in management consulting today in advocating breaking down silos
- We use a generations network to argue org can actually benefit from silos compared with fully transparent data sharing

## Application 2: Information Silos in Organizations



### Corollary 2

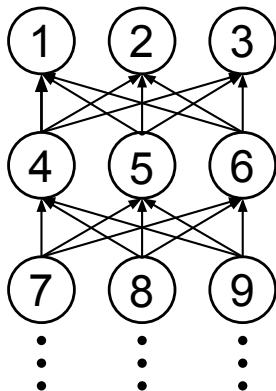
Suppose org consists of  $N$  silos with  $s_1, \dots, s_N$  agents per generation, plus 1 executive per generation. In the long run, silo  $n$  aggregates  $\frac{2s_n-1}{s_n} < \frac{2K-1}{K}$  signals per gen, while the executives aggregate  $\sum_{n=1}^N \frac{2s_n-1}{s_n}$  signals per gen.

## Application 2: Information Silos in Organizations

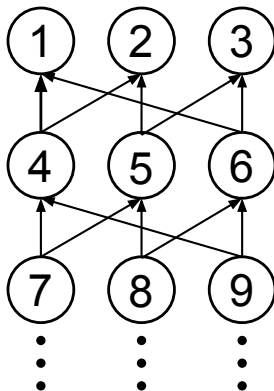
- Sacrifice rate of learning within silos to provide less confounded info to executives
- With full data sharing, workers in silos would learn better
  - ▶ Newcomers learn from predecessors across the org, instead of only predecessors from the same department
- But full data sharing slows down executives' learning
  - ▶ Actions from different silos conditionally independent
- Does breaking down silos help the org? It depends:
  - ▶ **NO** if org success closely identified with executives' actions
  - ▶ **YES** if everyone's action contributes to org's welfare
  - ▶ Negative case studies cited by Tett (2015) and management consultants involve workers in silos who take actions that severely harm the company

## Which Network Leads to Faster Learning?

Network A



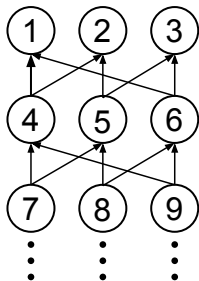
Network B



- **Network A** is the maximal generations network with  $K = 3$
- **Network B** puts agents in each gen into 3 slots,  $k \in \{1, 2, 3\}$ .  
 $k = 1$  sees 1 and 2,  $k = 2$  sees 2 and 3,  $k = 3$  sees 3 and 1.  
Less info confounding, but also fewer social observations.
- Need: aggregative efficiency on more general networks.

## Generations Network with Partial Observations

- Generations network with  $K$  agents per gen
- $\Psi_k \subseteq \{1, \dots, K\}$ , **observation set**, define which gen  $t - 1$  slots are observed by a gen  $t$  agent in slot  $k$
- Maximal generations network is the case of  $\Psi_k = \{1, \dots, K\}$



$$\Psi_1 = \{1, 2\},$$

$$\Psi_2 = \{2, 3\},$$

$$\Psi_3 = \{1, 3\}.$$

# Generations Network with Partial Observations

## Definition

The observation sets are **symmetric** if all agents observe  $d \geq 1$  neighbors and all pairs of distinct agents in the same generation share  $c$  common neighbors. That is, for all  $i_1 \neq i_2$  in same generation  $t \geq 2$ ,  $|N(i_1)| = d$  and  $|N(i_1) \cap N(i_2)| = c$ .

For example, “**Network B**” is symmetric with  $d = 2$ ,  $c = 1$ .

# Speed of Learning with Partial Observations

## Theorem 1

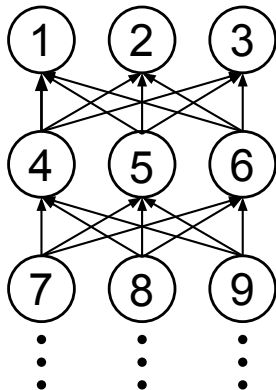
Suppose  $(\Psi_k)_k$  are symmetric. Then

$$\lim_{i \rightarrow \infty} (r_i/i) = \left( 1 + \frac{d^2 - d}{d^2 - d + c} \right) \frac{1}{K}.$$

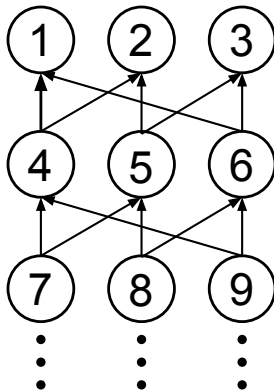
- Exact expression of aggregative efficiency for a broader class of generations networks
- Term in parenthesis increases in  $d$  and decreases in  $c$  — more obs speeds up rate of learning per gen but more confounding slows it down, all else equal
- Maximal gen network has the worst rate of learning, among all symmetric gen networks with same  $d$ 
  - ▶ Because actions very confounded in maximal gen network
- But Theorem 1 shows asymptotic bound of 2 signals per gen applies to **all** such networks, strengthening Proposition 4

## Which Network Leads to Faster Learning?

Network A



Network B



- Applying Theorem 1, aggregative efficiency is the same in **Network A** ( $d = 3, c = 3$ ) and **Network B** ( $d = 2, c = 1$ )!
- Extra social obs exactly cancel out reduced info content of each obs



# Social Planner's Benchmark

## Definition

$(\Psi_k)_k$  are **strongly connected** if for every  $1 \leq k_1 \leq k_2 \leq K$ , there exist  $t_1, t_2$  so that  $t_1 K + k_1$  is connected to  $t_2 K + k_2$  in  $M$ .

## Proposition 5

*Suppose  $(\Psi_k)_k$  are strongly connected and symmetric with  $c \geq 1$ . There is a log-linear strategy profile such that, for every  $K_0 < K$ , eventually agents' actions are more accurate<sup>1</sup> than aggregating  $K_0$  signals per generation.*

- A social planner can aggregate close to all signals
- Slow learning of Thm 1 not intrinsic limitation of gen networks

### ► Conclusion

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<sup>1</sup> $i$ 's action **more accurate than  $r$  signals** if it is more likely to lean towards the correct state than the action of someone who observes  $r$  indep signals.

## Aggregative Efficiency and Welfare Comparisons

Aggregative efficiency leads to two kinds of welfare comparisons

- Let  $v_i$  be expected eqm welfare of  $i$  (depends on  $M$  and  $1/\sigma^2$ )
- We always have  $-0.25 < v_i < 0$  for every  $i$
- Social learning **strongly attains**  $\underline{v}$  by agent  $l$  if  $l$  is the smallest integer s.t.  $v_i \geq \underline{v}$  for all  $i \geq l$
- Social learning **weakly attains**  $\underline{v}$  by agent  $i$  if  $i$  is the smallest integer s.t.  $v_i \geq \underline{v}$  (but later agents may do worse)

### Proposition 6

*Suppose aggregative efficiency is strictly positive in  $M$  and  $M'$ , and strictly higher in  $M$ . For every  $\underline{v} \in (-0.25, 0)$ , there exists  $\pi > 0$  so that if  $0 < 1/\sigma^2 \leq \pi$ , then social learning strongly attains  $\underline{v}$  in  $M$  by agent  $l$  and weakly attains  $\underline{v}$  by agent  $i$  in  $M'$ , with  $l < i$ .*

## Aggregative Efficiency and Welfare Comparisons

Now fix  $1/\sigma^2$ . Social planner could evaluate utility profiles  $v = (v_i)_{i \geq 1}$  using a social welfare function

$$\Lambda(v) = \sum_{i=1}^{\infty} \lambda_i v_i + \lambda_{\infty} \left( \lim_{i \rightarrow \infty} v_i \right)$$

- $\lambda_1, \lambda_2, \dots, \lambda_{\infty} \geq 0$  summable sequence of welfare weights
- $\lambda_{\infty}$  weight on “end of time”

“**Infinitely patient**” planner:  $\Lambda_{\infty}$  with  $\lambda_i = 0$  for  $i \in \mathbb{N}_+$ ,  $\lambda_{\infty} = 1$

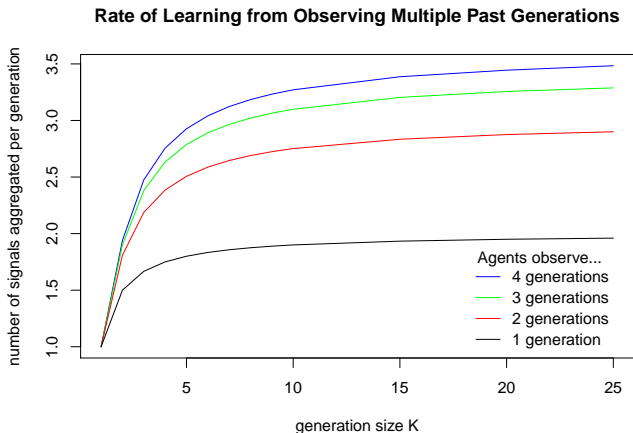
“**Very patient**” planner:  $\Lambda_T$  with  $\lambda_i = 0$  for  $i < T$ ,  $\lambda_i > 0$  for  $i \geq T$ , where  $T \in \mathbb{N}_+$  is large

### Proposition 7

*Suppose society learns completely in the long run in both  $M$  and  $M'$ , but aggregative efficiency is strictly higher in  $M$ . There exists  $\underline{T}$  so that if  $T \geq \underline{T}$ , then  $\Lambda_T$  is strictly higher on  $M$  than on  $M'$ , though  $\Lambda_{\infty}$  is indifferent between  $M$  and  $M'$ .*

## Simulation: Observing Multiple Past Generations

Each agent observes all predecessors from past  $\tau \geq 1$  generations



- Limited improvement in aggregative efficiency: removes some confounds but creates new ones

## Summary

- A tractable model of rational sequential learning that focuses on how the social network affects aggregative efficiency
- Exact aggregative efficiency in all generations networks with symmetric observation sets
- Significant info loss due to confounding: in any such network, each generation eventually aggregates no more than 2 signals
- Analytic expression for aggregative efficiency permits comparative statics and applications about org structure: mentorship, information silos

Thank you!